



Measure-preserving PL dynamical systems in \mathbb{R}^3 with bounded trajectories

Jeff Ford

10/2/17

Auburn University

We will demonstrate here the construction of a piecewise-linear, measure-preserving, non-singular dynamical system on \mathbb{R}^3 , with each trajectory contained in a bounded set. This is achieved by creating a nested sequence of *PL* approximations of solid tori, whose union is \mathbb{R}^3 . We then build a 1-foliation of each of the nested tori, which is modified using the slanted suspension construction of [GK],[GKK], to become a measured foliation of \mathbb{R}^3 , with each leaf contained in a bounded set. Finally, the leaves in this measured foliation are used to create a *PL*, measure-preserving, non-singular, dynamical system, with each orbit contained in a bounded set.

- We assume all manifolds here are *PL* (piecewise-linear), and that they can be triangulated.

- We assume all manifolds here are *PL* (piecewise-linear), and that they can be triangulated.
- All functions are assumed to be *PL* homeomorphisms, meaning that they are linear on each simplex in our triangulation.

- A *continuous dynamical system* is a triple $(\mathbb{R}, \Omega, \pi)$, with Ω a topological space and $\pi : \mathbb{R} \times \Omega \rightarrow \Omega$, such that
 - π is continuous
 - For any $x \in \Omega$, and any $t_1, t_2 \in \mathbb{R}$, we have $\pi(0, x) = x$ and $\pi(t_1, \pi(t_2, x)) = \pi(t_1 + t_2, x)$.

- A *continuous dynamical system* is a triple $(\mathbb{R}, \Omega, \pi)$, with Ω a topological space and $\pi : \mathbb{R} \times \Omega \rightarrow \Omega$, such that
 - π is continuous
 - For any $x \in \Omega$, and any $t_1, t_2 \in \mathbb{R}$, we have $\pi(0, x) = x$ and $\pi(t_1, \pi(t_2, x)) = \pi(t_1 + t_2, x)$.
- We often write $\pi(t, x)$ as tx for simplicity.

- A *continuous dynamical system* is a triple $(\mathbb{R}, \Omega, \pi)$, with Ω a topological space and $\pi : \mathbb{R} \times \Omega \rightarrow \Omega$, such that
 - π is continuous
 - For any $x \in \Omega$, and any $t_1, t_2 \in \mathbb{R}$, we have $\pi(0, x) = x$ and $\pi(t_1, \pi(t_2, x)) = \pi(t_1 + t_2, x)$.
- We often write $\pi(t, x)$ as tx for simplicity.
- $\gamma(x) = \{tx : t \in \mathbb{R}\}$ is the *trajectory* of x . This set may also be referred to as the *orbit* of x .

- A *continuous dynamical system* is a triple $(\mathbb{R}, \Omega, \pi)$, with Ω a topological space and $\pi : \mathbb{R} \times \Omega \rightarrow \Omega$, such that
 - π is continuous
 - For any $x \in \Omega$, and any $t_1, t_2 \in \mathbb{R}$, we have $\pi(0, x) = x$ and $\pi(t_1, \pi(t_2, x)) = \pi(t_1 + t_2, x)$.
- We often write $\pi(t, x)$ as tx for simplicity.
- $\gamma(x) = \{tx : t \in \mathbb{R}\}$ is the *trajectory* of x . This set may also be referred to as the *orbit* of x .
- A point $x \in \Omega$ is a *fixed point* if $x = tx$ for all $t \in \mathbb{R}$.

- A *continuous dynamical system* is a triple $(\mathbb{R}, \Omega, \pi)$, with Ω a topological space and $\pi : \mathbb{R} \times \Omega \rightarrow \Omega$, such that
 - π is continuous
 - For any $x \in \Omega$, and any $t_1, t_2 \in \mathbb{R}$, we have $\pi(0, x) = x$ and $\pi(t_1, \pi(t_2, x)) = \pi(t_1 + t_2, x)$.
- We often write $\pi(t, x)$ as tx for simplicity.
- $\gamma(x) = \{tx : t \in \mathbb{R}\}$ is the *trajectory* of x . This set may also be referred to as the *orbit* of x .
- A point $x \in \Omega$ is a *fixed point* if $x = tx$ for all $t \in \mathbb{R}$.
- $(\mathbb{R}, \Omega, \pi)$ is a *non-singular* dynamical system if it contains no fixed points.

- Define $\pi^{-1} : \mathbb{R} \times \Omega \rightarrow \Omega$ by $\pi^{-1}(t, x) = \pi(-t, x)$.

- Define $\pi^{-1} : \mathbb{R} \times \Omega \rightarrow \Omega$ by $\pi^{-1}(t, x) = \pi(-t, x)$.
- For any $A \subset \Omega$, define $\pi(t, A) = \{\pi(t, x) : x \in A\}$.

- Define $\pi^{-1} : \mathbb{R} \times \Omega \rightarrow \Omega$ by $\pi^{-1}(t, x) = \pi(-t, x)$.
- For any $A \subset \Omega$, define $\pi(t, A) = \{\pi(t, x) : x \in A\}$.
- If μ is a measure on Ω , such that for any measurable set $A \subset \Omega$ and any $t \in \mathbb{R}$, $\mu(A) = \mu(\pi^{-1}(t, A))$, then $(\mathbb{R}, \Omega, \pi, \mu)$ is a *measure-preserving* dynamical system [Ro].

Measureable dynamics

- Define $\pi^{-1} : \mathbb{R} \times \Omega \rightarrow \Omega$ by $\pi^{-1}(t, x) = \pi(-t, x)$.
- For any $A \subset \Omega$, define $\pi(t, A) = \{\pi(t, x) : x \in A\}$.
- If μ is a measure on Ω , such that for any measurable set $A \subset \Omega$ and any $t \in \mathbb{R}$, $\mu(A) = \mu(\pi^{-1}(t, A))$, then $(\mathbb{R}, \Omega, \pi, \mu)$ is a *measure-preserving* dynamical system [Ro].
- Since our manifolds are all *PL*, we assume our measures are *simplicial*, that is, the measure is equivalent to Lebesgue measure on each simplex (after embedding into \mathbb{R}^n under a chart map.)

Thanks to G. Kuperberg [GK], we have a a piecewise-linear analog of the results of Moser [Mos], which allows us to move between simplicial measures on PL manifolds.

Thanks to G. Kuperberg [GK], we have a a piecewise-linear analog of the results of Moser [Mos], which allows us to move between simplicial measures on PL manifolds.

Theorem

Two simplicial measures on a connected, compact, PL -manifold, with the same total volume, are equivalent under a PL homeomorphism.

Moreover, any simplicial measure is locally PL -Lebesgue.

Thanks to G. Kuperberg [GK], we have a a piecewise-linear analog of the results of Moser [Mos], which allows us to move between simplicial measures on PL manifolds.

Theorem

Two simplicial measures on a connected, compact, PL -manifold, with the same total volume, are equivalent under a PL homeomorphism.

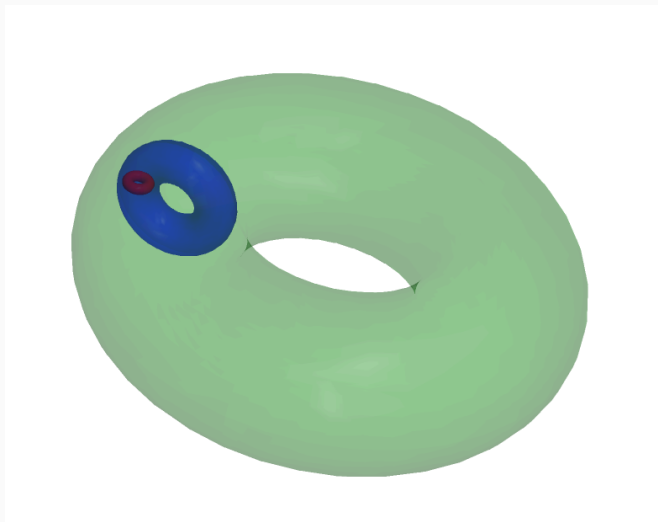
Moreover, any simplicial measure is locally PL -Lebesgue.

Starting point for the construction

Inspiration for the construction comes from Jones and Yorke [JY].

Starting point for the construction

Inspiration for the construction comes from Jones and Yorke [JY].



Make the tori PL

- By a PL torus, we mean a triangulated torus with 16 subdivisions around the major circumference, and 64 subdivisions around the minor circumference.

Make the tori PL

- By a PL torus, we mean a triangulated torus with 16 subdivisions around the major circumference, and 64 subdivisions around the minor circumference.
- Let T_0^{PL} be a PL torus, in the xy -plane, centered at the origin, with minor radius $m_0 = 1$ and major radius $M_0 = 4$.

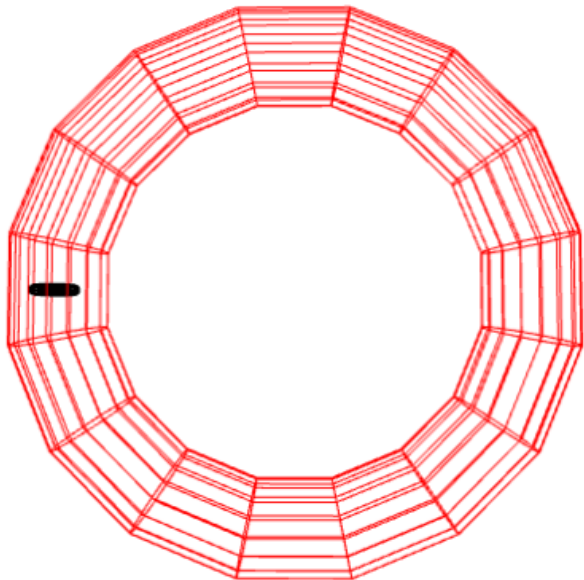
Make the tori PL

- By a PL torus, we mean a triangulated torus with 16 subdivisions around the major circumference, and 64 subdivisions around the minor circumference.
- Let T_0^{PL} be a PL torus, in the xy -plane, centered at the origin, with minor radius $m_0 = 1$ and major radius $M_0 = 4$.
- Let T_1^{PL} be a PL torus, in the yz -plane, centered at $(0,48,0)$, with minor radius $m_1 = 10$ and major radius $M_1 = 48$. Rotate the entire torus by an angle of $\pi/16$.

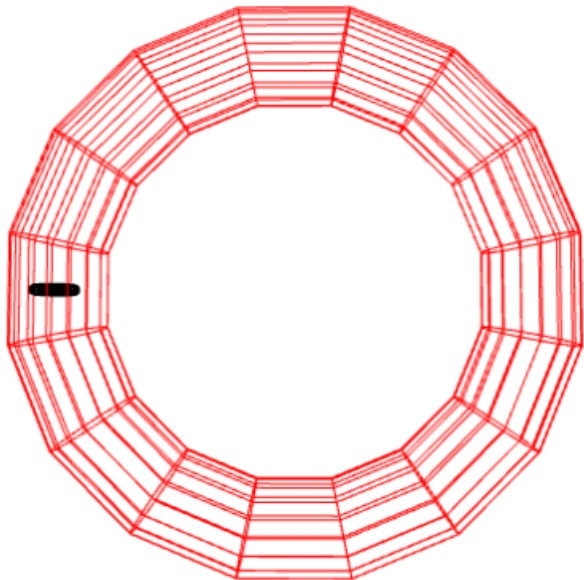
Make the tori PL

- By a PL torus, we mean a triangulated torus with 16 subdivisions around the major circumference, and 64 subdivisions around the minor circumference.
- Let T_0^{PL} be a PL torus, in the xy -plane, centered at the origin, with minor radius $m_0 = 1$ and major radius $M_0 = 4$.
- Let T_1^{PL} be a PL torus, in the yz -plane, centered at $(0,48,0)$, with minor radius $m_1 = 10$ and major radius $M_1 = 48$. Rotate the entire torus by an angle of $\pi/16$.
- Let T_n^{PL} be a PL torus, in the xy -plane if n is even, and the yz -plane if n is odd, centered at $(0,(4)12^n,0)$, with minor radius $m_n = \frac{5}{2}M_{n-1}$ and major radius $M_n = 12M_{n-1}$. Again, rotate by $\pi/16$ after each construction.

Make the tori PL



Make the tori PL



1-foliations

Let M be an n -manifold. Fix some indexing set A . Let $\mathcal{F} = \{L_\alpha : \alpha \in A\}$ be a collection of arcwise connected subsets of M . \mathcal{F} is a *1-dimensional foliation of M* if

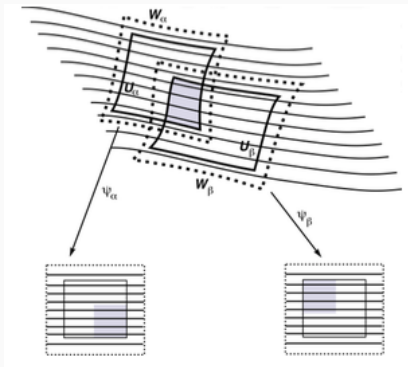
- (i) $L_\alpha \cap L_\beta = \emptyset$ for $\alpha \neq \beta$
- (ii) $\bigcup_{\alpha \in A} L_\alpha = M$.
- (iii) Given any point $p \in M$, there exists a chart of $(U_\lambda, \varphi_\lambda)$ about p , such that for L_α with $L_\alpha \cap U_\lambda \neq \emptyset$, each path component of $\varphi(L_\alpha \cap U_\lambda)$ is of the form

$$\{x_1 \in \varphi_\lambda(U_\lambda) : x_2 = c_1, x_3 = c_2, \dots, x_n = c_{n-1}\}$$

where each c_i is a constant determined by L_α .

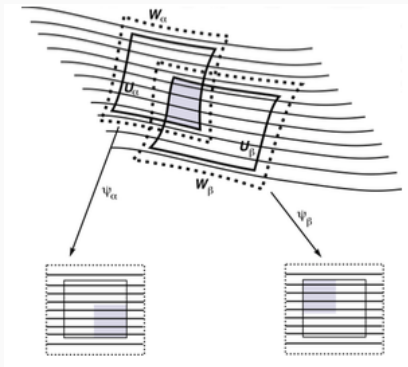
Each L_α is a *leaf* of the foliation \mathcal{F} . We can view the embeddings as splitting \mathbb{R}^n into two pieces, \mathbb{R} and \mathbb{R}^{n-1} . On \mathbb{R} , the coordinates of the embedding vary with L_α , but on \mathbb{R}^{n-1} , the coordinates are fixed.

Each L_α is a *leaf* of the foliation \mathcal{F} . We can view the embeddings as splitting \mathbb{R}^n into two pieces, \mathbb{R} and \mathbb{R}^{n-1} . On \mathbb{R} , the coordinates of the embedding vary with L_α , but on \mathbb{R}^{n-1} , the coordinates are fixed.



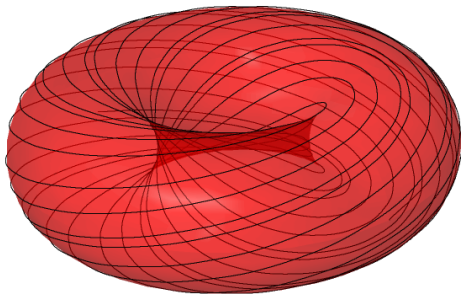
[H, LN]

Each L_α is a *leaf* of the foliation \mathcal{F} . We can view the embeddings as splitting \mathbb{R}^n into two pieces, \mathbb{R} and \mathbb{R}^{n-1} . On \mathbb{R} , the coordinates of the embedding vary with L_α , but on \mathbb{R}^{n-1} , the coordinates are fixed.



[H, LN] We say the foliation is *oriented* if the embedding preserves the usual orientation of \mathbb{R} [T].

Foliated torus



Measured Foliations

Begin with some manifold M and a 1-foliation \mathcal{F} .

- Take a collection of closed disks called *flow boxes* of the form $D_k \times D_{n-k}$, whose interiors cover M .

Measured Foliations

Begin with some manifold M and a 1-foliation \mathcal{F} .

- Take a collection of closed disks called *flow boxes* of the form $D_k \times D_{n-k}$, whose interiors cover M .
- Each \mathcal{L}_α passing through a flow box to intersect the box in a collection of horizontal disks $D_k \times \{y\}$.

Measured Foliations

Begin with some manifold M and a 1-foliation \mathcal{F} .

- Take a collection of closed disks called *flow boxes* of the form $D_k \times D_{n-k}$, whose interiors cover M .
- Each \mathcal{L}_α passing through a flow box to intersect the box in a collection of horizontal disks $D_k \times \{y\}$.
- A *transversal* T is a smooth $(n - k)$ -dimensional submanifold which is transverse to each \mathcal{L}_α .

Measured Foliations

Begin with some manifold M and a 1-foliation \mathcal{F} .

- Take a collection of closed disks called *flow boxes* of the form $D_k \times D_{n-k}$, whose interiors cover M .
- Each \mathcal{L}_α passing through a flow box to intersect the box in a collection of horizontal disks $D_k \times \{y\}$.
- A *transversal* T is a smooth $(n - k)$ -dimensional submanifold which is transverse to each \mathcal{L}_α .
- T is *small* if it can be surrounded by a single flow box.

Measured Foliations

Begin with some manifold M and a 1-foliation \mathcal{F} .

- Take a collection of closed disks called *flow boxes* of the form $D_k \times D_{n-k}$, whose interiors cover M .
- Each \mathcal{L}_α passing through a flow box to intersect the box in a collection of horizontal disks $D_k \times \{y\}$.
- A *transversal* T is a smooth $(n - k)$ -dimensional submanifold which is transverse to each \mathcal{L}_α .
- T is *small* if it can be surrounded by a single flow box.
- A *transverse measure* μ on \mathcal{F} is a function which assigns each small transversal a finite non-negative number[RS].

- μ must be additive on a union of transversals.

Measured Foliations

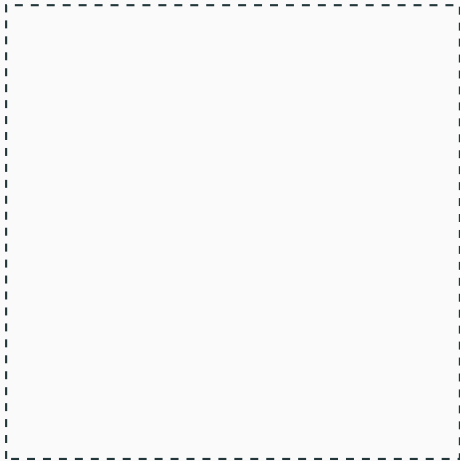
- μ must be additive on a union of transversals.
- Given two transversals, α, β , a measure μ is *invariant* if, when α and β are isotopic, with isotopy parallel to the foliation, then $\mu(\alpha) = \mu(\beta)$.

Measured Foliations

- μ must be additive on a union of transversals.
- Given two transversals, α, β , a measure μ is *invariant* if, when α and β are isotopic, with isotopy parallel to the foliation, then $\mu(\alpha) = \mu(\beta)$.
- Then the pair (\mathcal{F}, μ) is a *measured foliation*. [FLP]

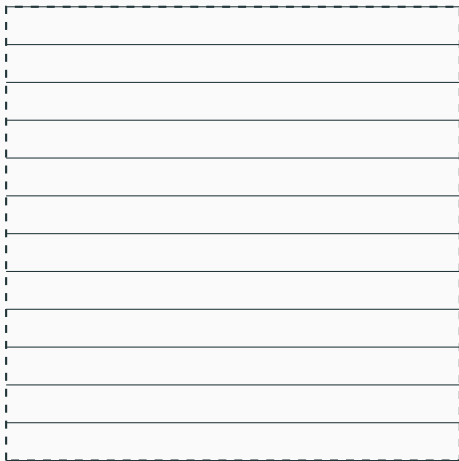
Example

Start with a flow box



Example

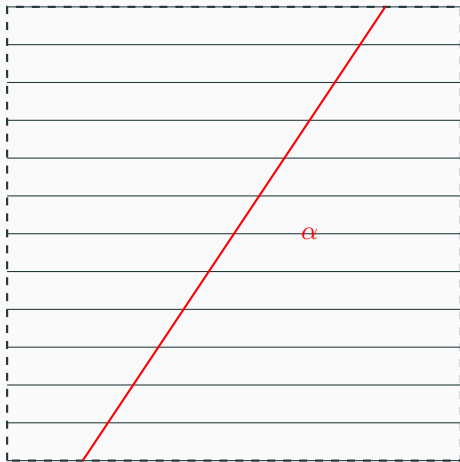
Only one coordinate changes on each leaf.



A diagram of a binary tree structure. The tree is represented by a vertical dashed line on the left and a vertical dashed line on the right. Between these two lines, there are 11 horizontal solid lines, each representing a leaf node. The lines are evenly spaced, creating 11 distinct horizontal slots for data.

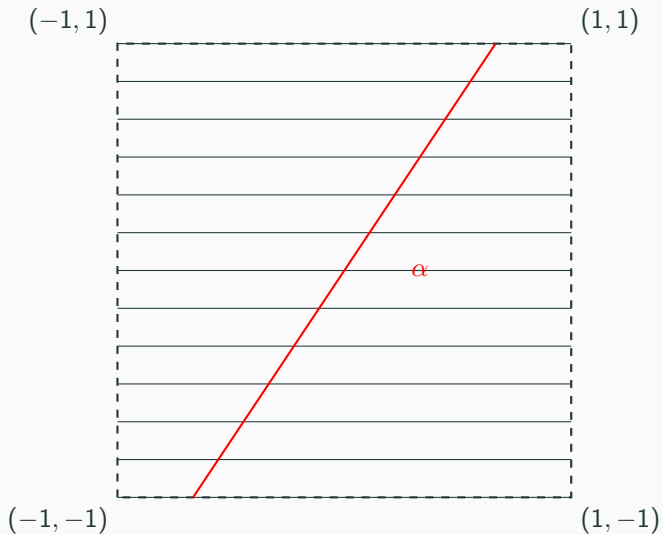
Example

Add in a transversal, which we call α .

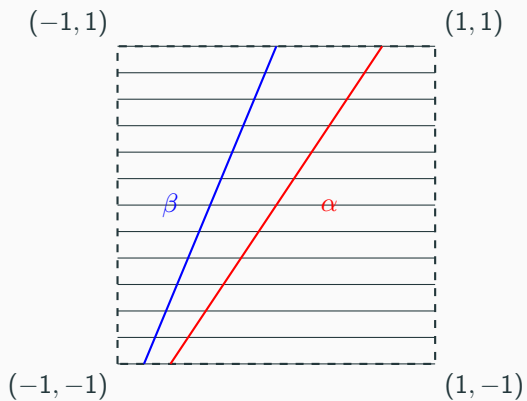


Example

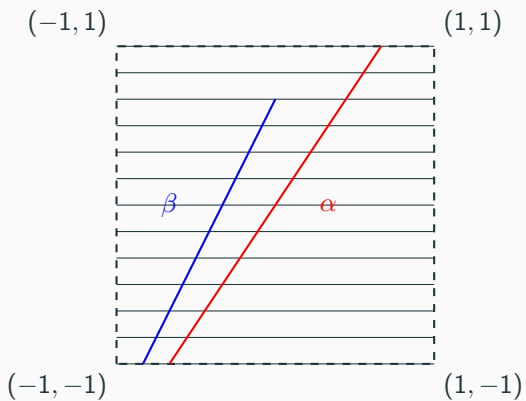
Add coordinates, and define $\mu(\alpha) = 2$



Isotopies of transversals

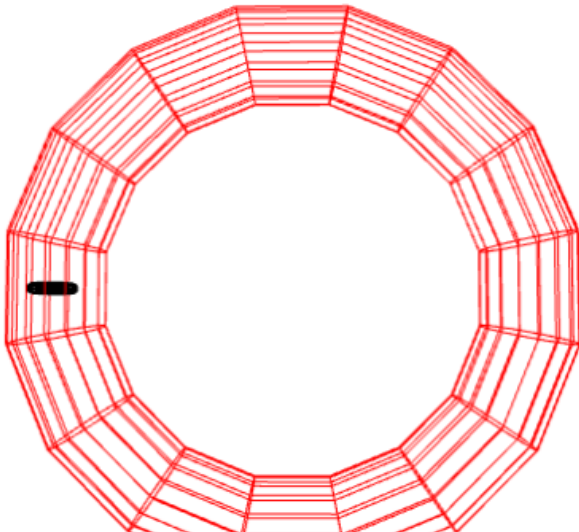


Isotopies of transversals



From foliations to dynamics

We can describe how to foliate our nested tori, but we need to be sure we can end up with a dynamical system to satisfy our theorem.



Hyperboloid Example

Let M be the hyperboloid of one sheet in \mathbb{R}^3 , given by the parametric equations

$$x = \sqrt{u^2 + 1} \cos(v)$$

$$y = \sqrt{u^2 + 1} \sin(v)$$

$$z = u$$

for $u \in [-1, 1]$ and $v \in [0, 2\pi]$.

Hyperboloid Example

Let M be the hyperboloid of one sheet in \mathbb{R}^3 , given by the parametric equations

$$x = \sqrt{u^2 + 1} \cos(v)$$

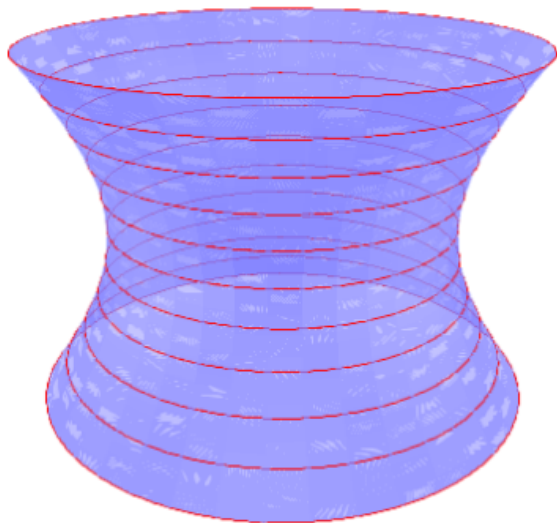
$$y = \sqrt{u^2 + 1} \sin(v)$$

$$z = u$$

for $u \in [-1, 1]$ and $v \in [0, 2\pi]$.

Assume M is foliated by circular leaves, lying parallel to the xy -plane

Hyperboloid Example



Hyperboloid Example

- Let α be a transversal on M .

Hyperboloid Example

- Let α be a transversal on M .
- Assume there exists a transversal β , with α isotopic to β . We must show that their transverse measures are equal.

Hyperboloid Example

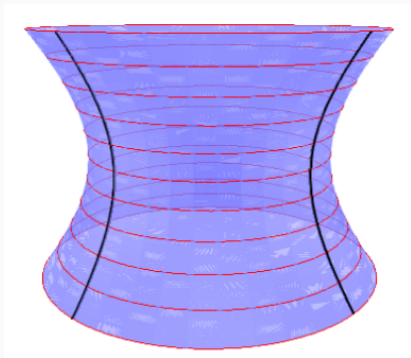
- Let α be a transversal on M .
- Assume there exists a transversal β , with α isotopic to β . We must show that their transverse measures are equal.
- Since our leaves are circular and parallel to the xy -plane in \mathbb{R}^3 , when the chart map is applied, the change in the y coordinate on each small transversal that makes up α will be kept constant during an isotopy parallel to the leaves that moves α to β . Therefore, $\mu(\alpha) = \mu(\beta)$.

Isotopic transversals

To give a specific example, let α be the transversal connecting the points $(\sqrt{2}, 0, 1)$ and $(\sqrt{2}, 0, -1)$, and β connect the points $(0, \sqrt{2}, 1)$ and $(0, \sqrt{2}, -1)$.

Isotopic transversals

To give a specific example, let α be the transversal connecting the points $(\sqrt{2}, 0, 1)$ and $(\sqrt{2}, 0, -1)$, and β connect the points $(0, \sqrt{2}, 1)$ and $(0, \sqrt{2}, -1)$.



Verifying the foliation is measured.

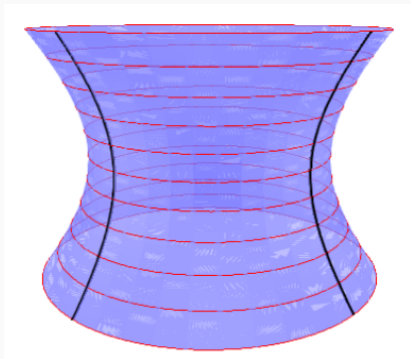
The function $f : \alpha \times [0, 1] \rightarrow \beta$ is

$$f(x, y, z, t) = (\sqrt{2} \cos(\frac{t\pi}{2}), \sqrt{2} \sin(\frac{t\pi}{2}), z).$$

Verifying the foliation is measured.

The function $f : \alpha \times [0, 1] \rightarrow \beta$ is

$$f(x, y, z, t) = (\sqrt{2} \cos(\frac{t\pi}{2}), \sqrt{2} \sin(\frac{t\pi}{2}), z).$$

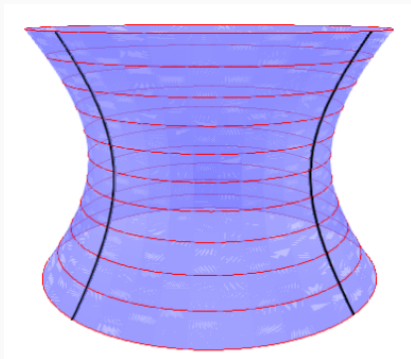


This gives α when $t = 0$, β when $t = 1$, and is an isotopy.

Verifying the foliation is measured.

The function $f : \alpha \times [0, 1] \rightarrow \beta$ is

$$f(x, y, z, t) = (\sqrt{2} \cos(\frac{t\pi}{2}), \sqrt{2} \sin(\frac{t\pi}{2}), z).$$



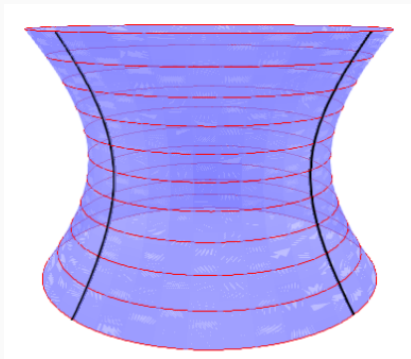
This gives α when $t = 0$, β when $t = 1$, and is an isotopy.

We can also see that $\mu(\alpha) = \mu(\beta)$.

Verifying the foliation is measured.

The function $f : \alpha \times [0, 1] \rightarrow \beta$ is

$$f(x, y, z, t) = (\sqrt{2} \cos(\frac{t\pi}{2}), \sqrt{2} \sin(\frac{t\pi}{2}), z).$$



This gives α when $t = 0$, β when $t = 1$, and is an isotopy.

We can also see that $\mu(\alpha) = \mu(\beta)$.

We conclude that (M, \mathcal{F}) is a measured foliation.

Getting to a dynamical system

- Each leaf in this foliation is circular.

Getting to a dynamical system

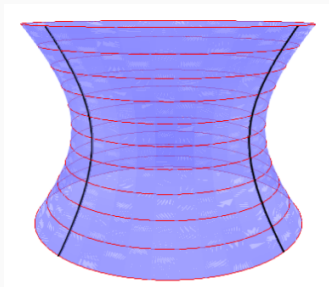
- Each leaf in this foliation is circular.
- Fix the set α as above.

Getting to a dynamical system

- Each leaf in this foliation is circular.
- Fix the set α as above.
- Define the length of a leaf in \mathcal{F} by fixing a point on the leaf in α and measuring the metric distance along the leaf, following the orientation, until the leaf intersects α again.

Getting to a dynamical system

- Each leaf in this foliation is circular.
- Fix the set α as above.
- Define the length of a leaf in \mathcal{F} by fixing a point on the leaf in α and measuring the metric distance along the leaf, following the orientation, until the leaf intersects α again.



α is transverse to all of \mathcal{F} , and each leaf in \mathcal{F} intersects α exactly once.

- For a given $p_0 \in M$, let $l(p_0)$ be the length of the leaf containing p_0 .

- For a given $p_0 \in M$, let $l(p_0)$ be the length of the leaf containing p_0 .
- For a point $p_0 \in M$, define $\pi : \mathbb{R} \times M \rightarrow M$, by letting $\pi(t, p_0)$ be the pre-image (under the chart map) of the point $\varphi_\lambda(p_0) + l(p_0)t$, which shifts the point along the image of the leaf $l(p_0)t$ units.

- For a given $p_0 \in M$, let $l(p_0)$ be the length of the leaf containing p_0 .
- For a point $p_0 \in M$, define $\pi : \mathbb{R} \times M \rightarrow M$, by letting $\pi(t, p_0)$ be the pre-image (under the chart map) of the point $\varphi_\lambda(p_0) + l(p_0)t$, which shifts the point along the image of the leaf $l(p_0)t$ units.
- Since the chart maps in the foliation are continuous, π is continuous.

- For a given $p_0 \in M$, let $l(p_0)$ be the length of the leaf containing p_0 .
- For a point $p_0 \in M$, define $\pi : \mathbb{R} \times M \rightarrow M$, by letting $\pi(t, p_0)$ be the pre-image (under the chart map) of the point $\varphi_\lambda(p_0) + l(p_0)t$, which shifts the point along the image of the leaf $l(p_0)t$ units.
- Since the chart maps in the foliation are continuous, π is continuous.
- $\pi(0, p_0) = p_0$ (since it is not translated along the leaf at all)

- For a given $p_0 \in M$, let $l(p_0)$ be the length of the leaf containing p_0 .
- For a point $p_0 \in M$, define $\pi : \mathbb{R} \times M \rightarrow M$, by letting $\pi(t, p_0)$ be the pre-image (under the chart map) of the point $\varphi_\lambda(p_0) + l(p_0)t$, which shifts the point along the image of the leaf $l(p_0)t$ units.
- Since the chart maps in the foliation are continuous, π is continuous.
- $\pi(0, p_0) = p_0$ (since it is not translated along the leaf at all)
- $\pi(t_1, (\pi(t_2, p_0))) = \pi(t_1 + t_2, p_0)$ (since two translations along \mathbb{R} are easily composed).

- For a given $p_0 \in M$, let $l(p_0)$ be the length of the leaf containing p_0 .
- For a point $p_0 \in M$, define $\pi : \mathbb{R} \times M \rightarrow M$, by letting $\pi(t, p_0)$ be the pre-image (under the chart map) of the point $\varphi_\lambda(p_0) + l(p_0)t$, which shifts the point along the image of the leaf $l(p_0)t$ units.
- Since the chart maps in the foliation are continuous, π is continuous.
- $\pi(0, p_0) = p_0$ (since it is not translated along the leaf at all)
- $\pi(t_1, (\pi(t_2, p_0))) = \pi(t_1 + t_2, p_0)$ (since two translations along \mathbb{R} are easily composed).
- Therefore the definition of a dynamical system is satisfied by (M, \mathbb{R}, π) .

Verification of measure-preserving

- We have μ as the transverse measure on \mathcal{F} .

Verification of measure-preserving

- We have μ as the transverse measure on \mathcal{F} .
- Let $A \subset M$.

Verification of measure-preserving

- We have μ as the transverse measure on \mathcal{F} .
- Let $A \subset M$.
- Let ω_M be the Riemannian volume form on M .

Verification of measure-preserving

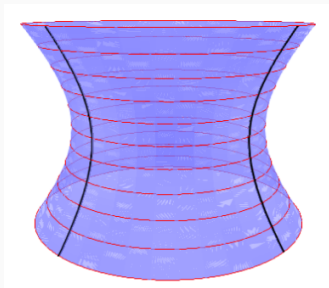
- We have μ as the transverse measure on \mathcal{F} .
- Let $A \subset M$.
- Let ω_M be the Riemannian volume form on M .
- Decompose A as a union of small transversals.

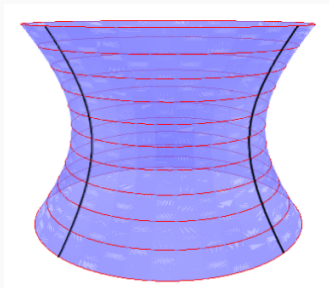
Verification of measure-preserving

- We have μ as the transverse measure on \mathcal{F} .
- Let $A \subset M$.
- Let ω_M be the Riemannian volume form on M .
- Decompose A as a union of small transversals.
- Think of points on M in cylindrical coordinates.

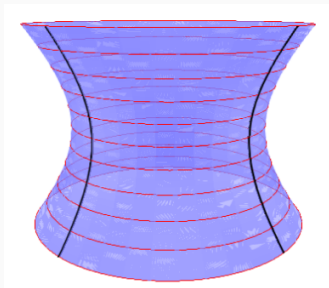
Verification of measure-preserving

- We have μ as the transverse measure on \mathcal{F} .
- Let $A \subset M$.
- Let ω_M be the Riemannian volume form on M .
- Decompose A as a union of small transversals.
- Think of points on M in cylindrical coordinates.

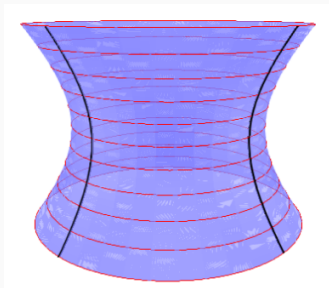




- Our chart maps preserve the orientation of leaves in the x direction, so $\pi^{-1}(t, A)$ will rotate A around M , scaled by the length of each leaf going through each point in A , so the change in θ between any two points in A is preserved under π^{-1} .



- Our chart maps preserve the orientation of leaves in the x direction, so $\pi^{-1}(t, A)$ will rotate A around M , scaled by the length of each leaf going through each point in A , so the change in θ between any two points in A is preserved under π^{-1} .
- For any fixed angle of rotation around the hyperboloid, the metric on M is determined by r and z , and that distance is represented by changes in the x -coordinates under the chart map.



- Our chart maps preserve the orientation of leaves in the x direction, so $\pi^{-1}(t, A)$ will rotate A around M , scaled by the length of each leaf going through each point in A , so the change in θ between any two points in A is preserved under π^{-1} .
- For any fixed angle of rotation around the hyperboloid, the metric on M is determined by r and z , and that distance is represented by changes in the x -coordinates under the chart map.
- The invariance of μ with respect to the x -direction after the chart map is applied, will preserve the change in the remaining components of ω_M under $\pi^{-1}(t, A)$.

- Therefore each point in A will have its r and z coordinates preserved under $f^{-1}(t, A)$, and while each point will move a different distance, the change in the angle θ will be the same for each point. We conclude that ω_M is preserved under $\pi^{-1}(t, A)$ for any choice of $t \in \mathbb{R}$.

- Therefore each point in A will have its r and z coordinates preserved under $f^{-1}(t, A)$, and while each point will move a different distance, the change in the angle θ will be the same for each point. We conclude that ω_M is preserved under $\pi^{-1}(t, A)$ for any choice of $t \in \mathbb{R}$.
- Let ν be the measure associated with ω_M , then, (M, \mathbb{R}, f, ν) is a measure-preserving dynamical system.

Theorem

An oriented, measured, 1-foliation (\mathcal{F}, μ) on a compact, connected, orientable 3-manifold, yields a measure-preserving dynamical system.

Theorem

An oriented, measured, 1-foliation (\mathcal{F}, μ) on a compact, connected, orientable 3-manifold, yields a measure-preserving dynamical system.

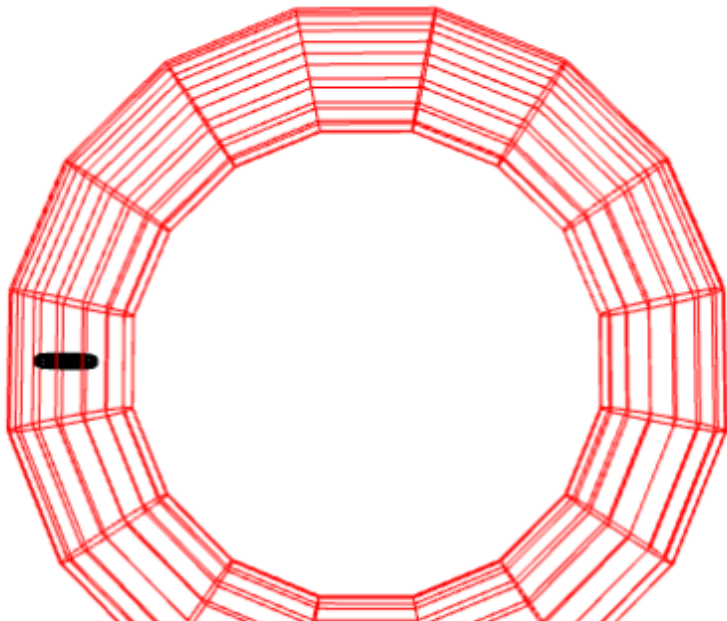
This is a simplification of the results in Plante [P], Walczak [Wa], and Hurder [H, LN]. It is sufficient for our purposes here.

Theorem

An oriented, measured, 1-foliation (\mathcal{F}, μ) on a compact, connected, orientable 3-manifold, yields a measure-preserving dynamical system.

This is a simplification of the results in Plante [P], Walczak [Wa], and Hurder [H, LN]. It is sufficient for our purposes here. \mathbb{R}^3 of course is not compact, but we can work around this.

Back to the tori



Slanted suspensions

- Let H be a compact manifold, with $f : H \times [a, b] \rightarrow H \times [a, b]$ be a PL homeomorphism.

Slanted suspensions

- Let H be a compact manifold, with $f : H \times [a, b] \rightarrow H \times [a, b]$ be a PL homeomorphism.
- Fix a real number $t \in (0, 1)$.

Slanted suspensions

- Let H be a compact manifold, with $f : H \times [a, b] \rightarrow H \times [a, b]$ be a PL homeomorphism.
- Fix a real number $l \in (0, 1)$.
- For each fixed point $x \in H$ and $y \in [a, b]$, let $L_{xy} = \{(x, y + lz, z) : y + lz \in [a, b] \text{ and } z \in [0, 1]\}$.

Slanted suspensions

- Let H be a compact manifold, with $f : H \times [a, b] \rightarrow H \times [a, b]$ be a PL homeomorphism.
- Fix a real number $l \in (0, 1)$.
- For each fixed point $x \in H$ and $y \in [a, b]$, let
 $L_{xy} = \{(x, y + lz, z) : y + lz \in [a, b] \text{ and } z \in [0, 1]\}$.
- $\mathcal{L} = \{L_{xy} : \forall (x, y) \in H \times [a, b]\}$ is a foliation of $H \times [a, b] \times [0, 1]$, with leaves oriented from $H \times [a, b] \times \{0\}$ to $H \times [a, b] \times \{1\}$.

Slanted suspensions

- Let H be a compact manifold, with $f : H \times [a, b] \rightarrow H \times [a, b]$ be a PL homeomorphism.
- Fix a real number $l \in (0, 1)$.
- For each fixed point $x \in H$ and $y \in [a, b]$, let $L_{xy} = \{(x, y + lz, z) : y + lz \in [a, b] \text{ and } z \in [0, 1]\}$.
- $\mathcal{L} = \{L_{xy} : \forall (x, y) \in H \times [a, b]\}$ is a foliation of $H \times [a, b] \times [0, 1]$, with leaves oriented from $H \times [a, b] \times \{0\}$ to $H \times [a, b] \times \{1\}$.
- The *slanted suspension* of $H \times [a, b]$ with *slant* l is the foliation of the quotient space generated by the equivalence $(f(x, y), 0) \sim (x, y, 1)$, with a foliation \mathcal{F} induced by \mathcal{L} . [GKK]

Slanted suspensions

- Let H be a compact manifold, with $f : H \times [a, b] \rightarrow H \times [a, b]$ be a PL homeomorphism.
- Fix a real number $l \in (0, 1)$.
- For each fixed point $x \in H$ and $y \in [a, b]$, let
$$L_{xy} = \{(x, y + lz, z) : y + lz \in [a, b] \text{ and } z \in [0, 1]\}.$$
- $\mathcal{L} = \{L_{xy} : \forall (x, y) \in H \times [a, b]\}$ is a foliation of $H \times [a, b] \times [0, 1]$, with leaves oriented from $H \times [a, b] \times \{0\}$ to $H \times [a, b] \times \{1\}$.
- The *slanted suspension* of $H \times [a, b]$ with *slant* l is the foliation of the quotient space generated by the equivalence $(f(x, y), 0) \sim (x, y, 1)$, with a foliation \mathcal{F} induced by \mathcal{L} . [GKK]
- Denote this as $M_{\sim f, l}$.

Example

- H be a single point, and $[a, b] = [0, 1]$. We construct a slanted suspension with a singled fixed circular orbit.

Example

- H be a single point, and $[a, b] = [0, 1]$. We construct a slanted suspension with a singled fixed circular orbit.
- Let $f : [0, 1] \rightarrow [0, 1]$ be given by

$$f(x) = \begin{cases} 2x - 1 & \text{if } x \in [1/2, 1] \\ \frac{2x}{3} & \text{else} \end{cases}$$

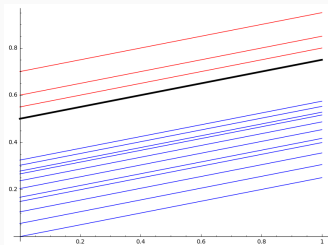
Example

- H be a single point, and $[a, b] = [0, 1]$. We construct a slanted suspension with a singled fixed circular orbit.
- Let $f : [0, 1] \rightarrow [0, 1]$ be given by

$$f(x) = \begin{cases} 2x - 1 & \text{if } x \in [1/2, 1] \\ \frac{2x}{3} & \text{else} \end{cases}$$

- Take the slanted suspension with slant $1/4$. The points 0 and 1 are fixed and $f(3/4) = 1/2$.

- There is a leaf from $(1/2, 0)$ to $(3/4, 1)$. This leaf comes from the slant, but the point $(3/4, 1)$ has the first coordinate shifted down by the same amount as the slant of the suspension. Thus $(3/4, 1)$ is identified with $(1/2, 0)$, creating a fixed circular leaf in the foliation.



Theorem

Let M be a 2 dimensional PL-manifold, μ a simplicial measure on M , and f a measure-preserving PL-homeomorphism on M . Then the foliation $M_{\sim, f, l}$ given by the slanted suspension of M under f , with slant l , is measured.

We wish to describe the boundary of a PL n -manifold M in terms of the foliation as being *parallel boundary* or *transverse boundary*. [GKK]

Flow bordisms and plugs

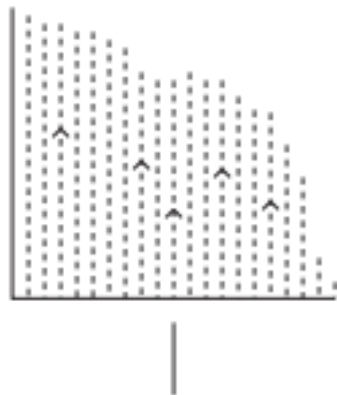
We wish to describe the boundary of a *PL* n -manifold M in terms of the foliation as being *parallel boundary* or *transverse boundary*. [GKK]

- The parallel boundary is a subset of the boundary of M such that the embedding of the foliation into the upper half-space of \mathbb{R}^n is modeled by a foliation consisting entirely of horizontal lines.
- The transverse boundary is the subset where the same embedding consists entirely of vertical lines.
- A manifold may also be said to have *corners*, if the boundary of the manifold is piecewise of the same smoothness category as the manifold itself.

Parallel boundary

Corner separation

Transverse boundary



[GK]

Given a connected, compact manifold P , a *flow bordism* \mathcal{P} is an oriented 1-foliation of P , such that all boundary of P is either transverse, parallel, or corners [GKK].

Given a connected, compact manifold P , a *flow bordism* \mathcal{P} is an oriented 1-foliation of P , such that all boundary of P is either transverse, parallel, or corners [GKK].

Let F_- be the closure of the transverse boundary oriented inwards, and F_+ be the closure of the transverse boundary oriented outwards. We have two additional properties in which we are interested.

- (i) There exists an infinite leaf with an endpoint in F_-
- (ii) There exists a manifold F and two homeomorphisms $\alpha_- : F \rightarrow F_-$, $\alpha_+ : F \rightarrow F_+$ such that if $\alpha_+(p)$ and $\alpha_-(q)$ are endpoints of a leaf of \mathcal{P} , then $p = q$.

- If a flow bordism satisfies condition (i), but not condition (ii), it is a *semi-plug*.
- A flow bordism which satisfies (ii) but not (i) is an *un-plug*.
- If \mathcal{P} has properties (i) and (ii), it is a *plug*.
- If \mathcal{P} is a plug, the manifold P is the *support* of \mathcal{P} .

[GKK]

Modification of a foliation using a plug requires the operation of *insertion*. Let \mathcal{P} be a flow bordism, and \mathcal{F} a foliation on some manifold M .

- An *insertion map* is an embedding of \mathcal{P} , in which both F_- and F_+ are transverse to \mathcal{F} .
- A flow bordism \mathcal{P} is *insertible* if there is an embedding of \mathcal{P} into \mathbb{R}^n which is transverse to vertical lines [GKK].

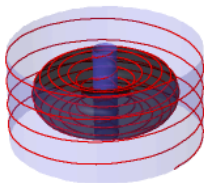
Modification of a foliation using a plug requires the operation of *insertion*. Let \mathcal{P} be a flow bordism, and \mathcal{F} a foliation on some manifold M .

- An *insertion map* is an embedding of \mathcal{P} , in which both F_- and F_+ are transverse to \mathcal{F} .
- A flow bordism \mathcal{P} is *insertible* if there is an embedding of \mathcal{P} into \mathbb{R}^n which is transverse to vertical lines [GKK].

We are looking for a way to modify an existing foliation, by taking leaves whose image under the chart map is that of vertical lines in \mathbb{R}^n , and replacing a portion of these leaves with the leaves in our flow bordism.

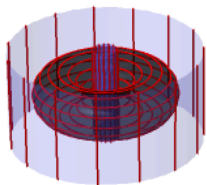
A flow bordism with a torus in the middle

We will construct a slanted suspension that gives us a PL version of this.



A flow bordism with a torus in the middle

We are looking for a PL way to make this sort of transformation, to get the parallel boundary we need..



Theorem

Let $M = [a, b] \times [c, d]$, and $f : M \rightarrow M$ a PL-homeomorphism. Take the slanted suspension of M with slant l . If for all $p \in \partial M$, $f(p) \neq p - l$, then $M_{\sim, f, l}$ may be made into a flow bordism, via a leaf-preserving map $g : M_{\sim, f, l} \rightarrow M_{\sim, f, l}$. Furthermore, if $M_{\sim, f, l}$ is a measured-foliation, g may be chosen such that $g(M_{\sim, f, l})$ remains measured.

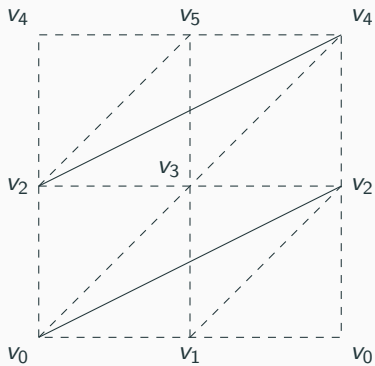
Theorem

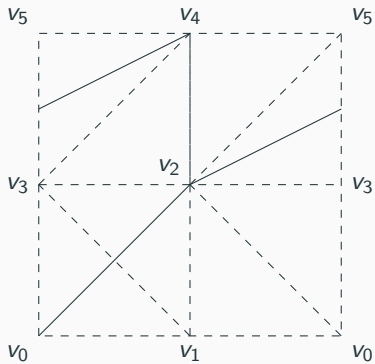
Let $M = [a, b] \times [c, d]$, and $f : M \rightarrow M$ a PL-homeomorphism. Take the slanted suspension of M with slant l . If for all $p \in \partial M$, $f(p) \neq p - l$, then $M_{\sim, f, l}$ may be made into a flow bordism, via a leaf-preserving map $g : M_{\sim, f, l} \rightarrow M_{\sim, f, l}$. Furthermore, if $M_{\sim, f, l}$ is a measured-foliation, g may be chosen such that $g(M_{\sim, f, l})$ remains measured.

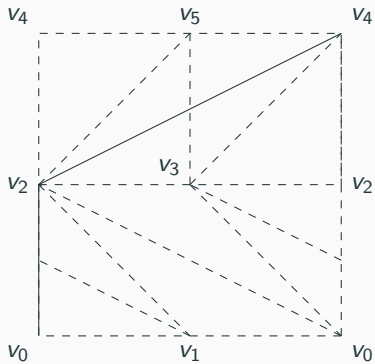
Corollary

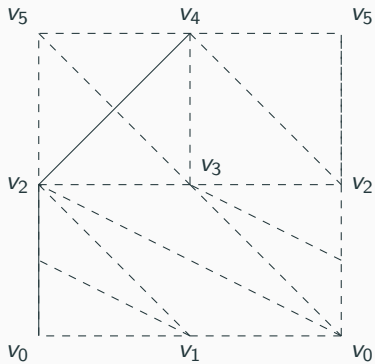
A PL flow bordism, with an invariant transverse measure, admits a PL dynamical system, which preserves measure.

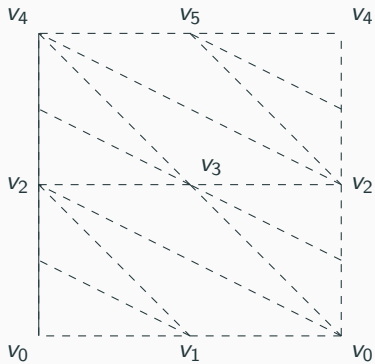
Example









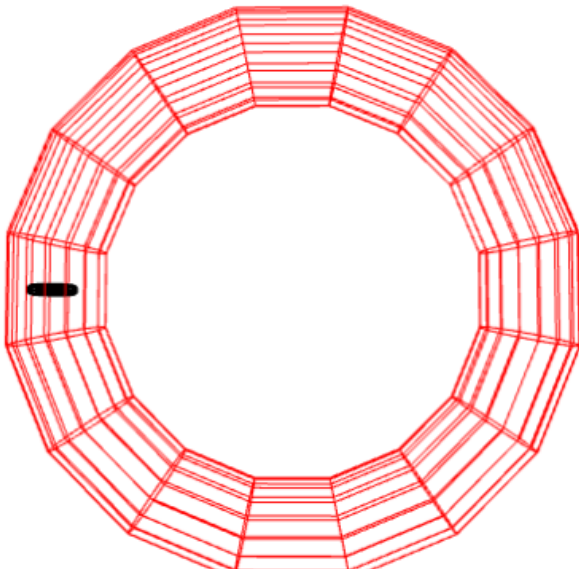


Building the main result

- Start with the nested tori defined earlier

Building the main result

- Start with the nested tori defined earlier



Building the main result

- Start with the nested tori defined earlier.
- Use the slanted suspension to build a flow bordism that can be inserted around each torus.

Building the main result

- Start with the nested tori defined earlier.
- Use the slanted suspension to build a flow bordism that can be inserted around each torus.
- Show that the insertion doesn't change the topology of \mathbb{R}^3 .

Building the main result

- Start with the nested tori defined earlier.
- Use the slanted suspension to build a flow bordism that can be inserted around each torus.
- Show that the insertion doesn't change the topology of \mathbb{R}^3 .
- Verify that the foliation is still measured on all of \mathbb{R}^3 .

Building the main result

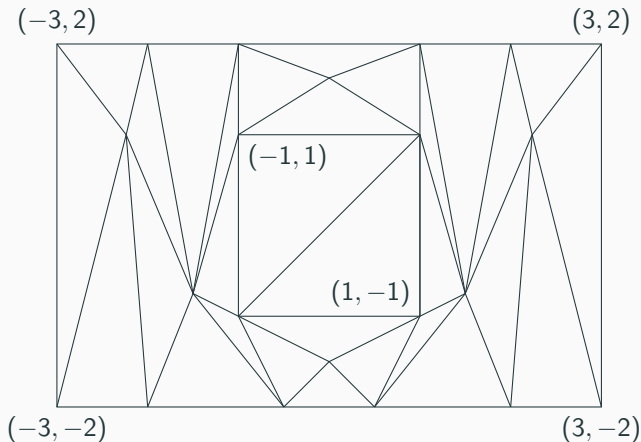
- Start with the nested tori defined earlier.
- Use the slanted suspension to build a flow bordism that can be inserted around each torus.
- Show that the insertion doesn't change the topology of \mathbb{R}^3 .
- Verify that the foliation is still measured on all of \mathbb{R}^3 .

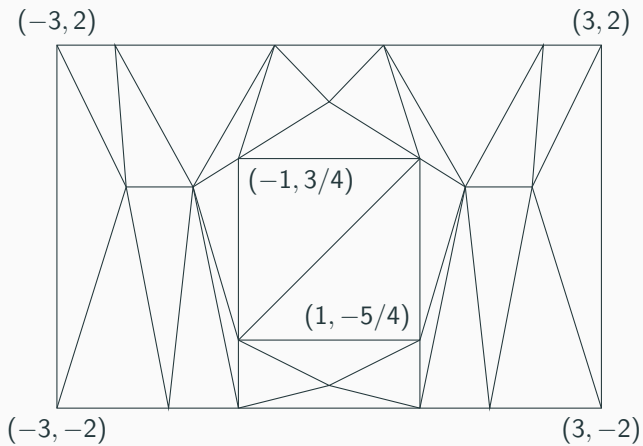
Building our slanted suspension

Let $M = [-3, 3] \times [-2, 2]$. Triangulate M , and let $f : M \rightarrow M$ be the *PL* homeomorphism, which preserves area on 2-simplices, and shifts the vertices of the square $[-1, 1] \times [-1, 1]$ region down $1/4$.

Building our slanted suspension

Let $M = [-3, 3] \times [-2, 2]$. Triangulate M , and let $f : M \rightarrow M$ be the *PL* homeomorphism, which preserves area on 2-simplices, and shifts the vertices of the square $[-1, 1] \times [-1, 1]$ region down $1/4$.





- Take the slanted suspension $M_{\sim, f, 1/4}$

Following the leaves

- Take the slanted suspension $M_{\sim, f, 1/4}$
- f preserves area on the 2-simplices here, so the slanted suspension is a measured foliation.

Following the leaves

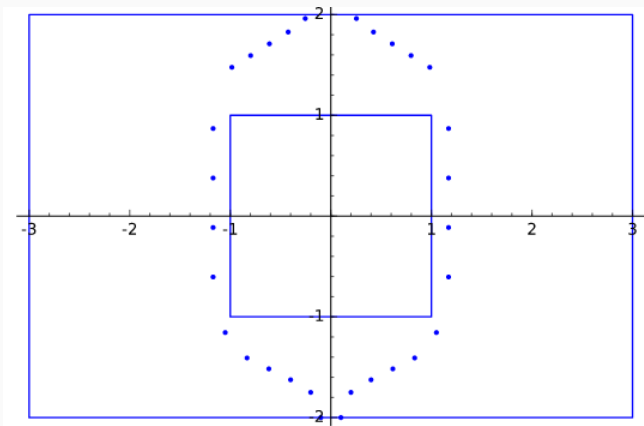
- Take the slanted suspension $M_{\sim, f, 1/4}$
- f preserves area on the 2-simplices here, so the slanted suspension is a measured foliation.
- f is the identity on the boundary of M , so the conditions in our earlier theorem are satisfied, and $(M_{\sim, f, 1/4}$ can be made into a measured flow bordism.

Following the leaves

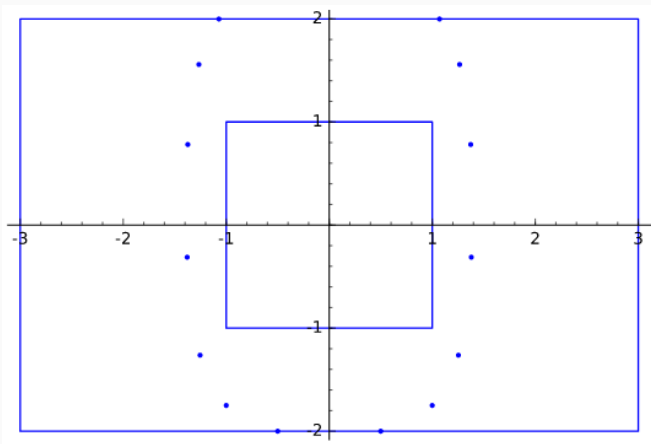
- Take the slanted suspension $M_{\sim, f, 1/4}$
- f preserves area on the 2-simplices here, so the slanted suspension is a measured foliation.
- f is the identity on the boundary of M , so the conditions in our earlier theorem are satisfied, and $(M_{\sim, f, 1/4}$ can be made into a measured flow bordism.
- The vertices of the square $[-1, 1] \times [-1, 1]$ are shifted down by $1/4$, and the slant of the suspension is $1/4$, so all leaves with points in the boundary of this square are circular.

Following the leaves

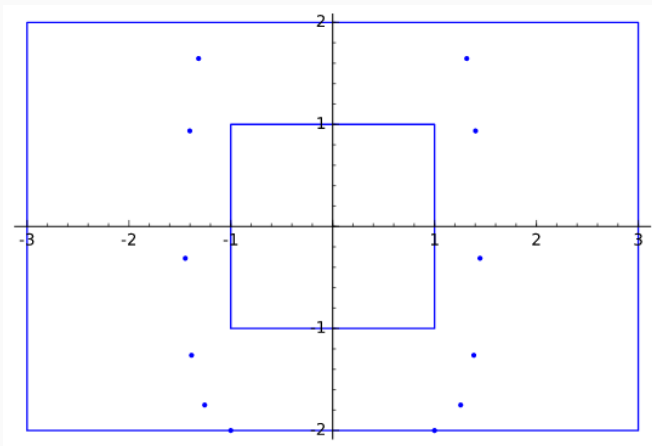
- Take the slanted suspension $M_{\sim, f, 1/4}$
- f preserves area on the 2-simplices here, so the slanted suspension is a measured foliation.
- f is the identity on the boundary of M , so the conditions in our earlier theorem are satisfied, and $(M_{\sim, f, 1/4}$ can be made into a measured flow bordism.
- The vertices of the square $[-1, 1] \times [-1, 1]$ are shifted down by $1/4$, and the slant of the suspension is $1/4$, so all leaves with points in the boundary of this square are circular.
- We can use a Poincare return map to see where the leaves intersect M at each iteration.



Trajectories originating at $(0.1, -2)$ and $(-0.1, -2)$



Trajectories originating at $(1/2, -2)$ and $(-1/2, -2)$



Trajectories originating at $(1,-2)$ and $(-1,-2)$

Removing tori from the slanted suspensions

- Our slanted suspension gives us a measured flow bordism.

Removing tori from the slanted suspensions

- Our slanted suspension gives us a measured flow bordism.
- In the middle of each of these slanted suspensions, there is a PL solid torus, whose boundary is foliated by circular leaves.

Removing tori from the slanted suspensions

- Our slanted suspension gives us a measured flow bordism.
- In the middle of each of these slanted suspensions, there is a PL solid torus, whose boundary is foliated by circular leaves.
- Scale up the size of the flow bordism until the total volume of the torus in the middle and the total volume of T_i^{PL} are the same, so we can use G. Kuperberg's theorem from earlier.

Removing tori from the slanted suspensions

- Our slanted suspension gives us a measured flow bordism.
- In the middle of each of these slanted suspensions, there is a PL solid torus, whose boundary is foliated by circular leaves.
- Scale up the size of the flow bordism until the total volume of the torus in the middle and the total volume of T_i^{PL} are the same, so we can use G. Kuperberg's theorem from earlier.
- If we can carefully remove that torus, we can insert scaled copies of the slanted suspension around each of the nested tori in our earlier construction.

Removing tori from the slanted suspensions

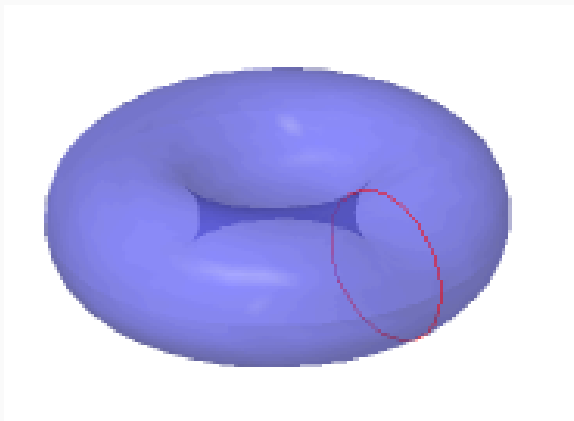
- Our slanted suspension gives us a measured flow bordism.
- In the middle of each of these slanted suspensions, there is a PL solid torus, whose boundary is foliated by circular leaves.
- Scale up the size of the flow bordism until the total volume of the torus in the middle and the total volume of T_i^{PL} are the same, so we can use G. Kuperberg's theorem from earlier.
- If we can carefully remove that torus, we can insert scaled copies of the slanted suspension around each of the nested tori in our earlier construction.
- We were careful to construct our earlier foliation so that all of the leaves near each nested torus are vertical, so our flow bordism will insert nicely.

Dehn Surgery

- Begin with a 3-manifold, and pick a solid torus in it's interior.
- Identify a closed curve on the boundary of the torus, the *meridian*, which bounds a disc.

Dehn Surgery

- Begin with a 3-manifold, and pick a solid torus in it's interior.
- Identify a closed curve on the boundary of the torus, the *meridian*, which bounds a disc.



Dehn Surgery

- Take another circle in the boundary of a torus, the *longitude*, which may or may not equal the meridian.

Dehn Surgery

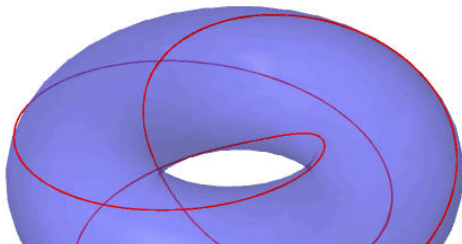
- Take another circle in the boundary of a torus, the *longitude*, which may or may not equal the meridian.
- By removing the torus from the 3-manifold, and gluing in a new one, with the longitude glued along the meridian, we effect a *Dehn Surgery* [G].

Dehn Surgery

- Take another circle in the boundary of a torus, the *longitude*, which may or may not equal the meridian.
- By removing the torus from the 3-manifold, and gluing in a new one, with the longitude glued along the meridian, we effect a *Dehn Surgery* [G].
- Dehn Surgery can change the topology of the manifold [L]. We make careful choices to avoid this.

Dehn Surgery

- Take another circle in the boundary of a torus, the *longitude*, which may or may not equal the meridian.
- By removing the torus from the 3-manifold, and gluing in a new one, with the longitude glued along the meridian, we effect a *Dehn Surgery* [G].
- Dehn Surgery can change the topology of the manifold [L]. We make careful choices to avoid this.



- In our construction, we will choose a meridian on the boundary of each torus in our nested tori.

- In our construction, we will choose a meridian on the boundary of each torus in our nested tori.
- The longitude for the torus removed from the interior of our slanted suspension flow bordism will be chosen to match the meridian on the nested tori.

- In our construction, we will choose a meridian on the boundary of each torus in our nested tori.
- The longitude for the torus removed from the interior of our slanted suspension flow bordism will be chosen to match the meridian on the nested tori.
- This ensures that our gluing does not change the topology of \mathbb{R}^3 .

Summary

- Start with our nested sequence of tori (T_n^{PL}).

Summary

- Start with our nested sequence of tori (T_n^{PL}).
- Foliate each of these tori by "circles".

Summary

- Start with our nested sequence of tori (T_n^{PL}).
- Foliate each of these tori by "circles".
- Scale up the flow bordisms from the slanted suspension, so that each can be inserted around T_i^{PL} .

Summary

- Start with our nested sequence of tori (T_n^{PL}).
- Foliate each of these tori by "circles".
- Scale up the flow bordisms from the slanted suspension, so that each can be inserted around T_i^{PL} .
- This agrees with the existing foliation, so the foliation of each torus is measured.

Summary

- Start with our nested sequence of tori (T_n^{PL}).
- Foliate each of these tori by "circles".
- Scale up the flow bordisms from the slanted suspension, so that each can be inserted around T_i^{PL} .
- This agrees with the existing foliation, so the foliation of each torus is measured.
- G. Kuperberg's theorem gives us that the simplicial measures can be made to agree.
- The tori are large enough and nested in such a way that the insertion around T_i^{PL} does not affect the leaves in the boundary of T_{i+1}^{PL} .

Summary

- Start with our nested sequence of tori (T_n^{PL}).
- Foliate each of these tori by "circles".
- Scale up the flow bordisms from the slanted suspension, so that each can be inserted around T_i^{PL} .
- This agrees with the existing foliation, so the foliation of each torus is measured.
- G. Kuperberg's theorem gives us that the simplicial measures can be made to agree.
- The tori are large enough and nested in such a way that the insertion around T_i^{PL} does not affect the leaves in the boundary of T_{i+1}^{PL} .
- Since each torus now possesses a measured-foliation, we have a non-singular, measure-preserving dynamical system on each torus.

Summary

- Start with our nested sequence of tori (T_n^{PL}).
- Foliate each of these tori by "circles".
- Scale up the flow bordisms from the slanted suspension, so that each can be inserted around T_i^{PL} .
- This agrees with the existing foliation, so the foliation of each torus is measured.
- G. Kuperberg's theorem gives us that the simplicial measures can be made to agree.
- The tori are large enough and nested in such a way that the insertion around T_i^{PL} does not affect the leaves in the boundary of T_{i+1}^{PL} .
- Since each torus now possesses a measured-foliation, we have a non-singular, measure-preserving dynamical system on each torus.
- All orbits beginning in one torus remain there, so all orbits are bounded.






Summary

- Start with our nested sequence of tori (T_n^{PL}).
- Foliate each of these tori by "circles".
- Scale up the flow bordisms from the slanted suspension, so that each can be inserted around T_i^{PL} .
- This agrees with the existing foliation, so the foliation of each torus is measured.
- G. Kuperberg's theorem gives us that the simplicial measures can be made to agree.
- The tori are large enough and nested in such a way that the insertion around T_i^{PL} does not affect the leaves in the boundary of T_{i+1}^{PL} .
- Since each torus now possesses a measured-foliation, we have a non-singular, measure-preserving dynamical system on each torus.
- All orbits beginning in one torus remain there, so all orbits are bounded.
- We therefore have a piecewise-linear, measure-preserving, non-singular dynamical system on \mathbb{R}^3 , with each trajectory contained in a bounded set.






References I

-  Fathi, A., Laudenbach, F., and Poénaru, V., *Thurston's Work on Surfaces*, translated by Djun Kim and Dan Margalit, Mathematical Notes, 48, Princeton University Press, 2012.
-  Gordon, C., *Dehn Surgery and 3-Manifolds*, IAS/Park City Mathematics Series, Volume 16, 2006.
-  Henriques, A., Pak, I., *Volume-preserving PL-maps between polyhedra*, in *Lectures on Discrete and Polyhedral Geometry*, <http://www.math.ucla.edu/~pak/geomp018.pdf>.
-  Hurder, S. Lectures on Foliation Dynamics, in *Foliations: Dynamics, Geometry, and Topology*, (Lopez, J.A., Nicolau, M. editors), Springer, Basel, 2014.

References II

-  Jones, G.S. and Yorke, J.A. *The existence and non-existence of critical points in bounded flows*, Journal of Differential Equations, **6**, 1969, 236-246.
-  Kuperberg, G. *A volume-preserving counterexample to the Seifert conjecture*, Comment. Math. Helv. **71**, 1996, no. 1, 70-97.
-  Kuperberg, K. and Kuperberg, G. *Generalized counterexamples to the Seifert conjecture*, Annals of Mathematics, Second Series, **143**, No. 3, 1996, 547-576.
-  Lickorish, W.B.R., *A representation of orientable combinatorial 3-manifolds*, Annals of Math., **76**, 1962, no. 3, 531-540.
-  Moser, J., *On the volume elements of a manifold*, Transactions of the American Mathematical Society, **120**, 1965, 286-294.

References III

-  Plante, J., *Foliations with measure preserving holonomy*, Annals of Mathematics, vol. 102, no. 2, 1975, 327-361.
-  Royden, H.L., Fitzpatrick, P.M., *Real Analysis, 4th edition*, Pearson, Boston, 2010
-  Ruelle, D. and Sullivan, D. *Currents, flows, and diffeomorphisms*, Topology, **14**, 1975, 319-327.
-  Tamura, I. *Topology of Foliations: An Introduction*, AMS, Providence, 1992.
-  Walczak, P., *Dynamics of foliations, groups and pseudogroups*, Birkhuser Verlag, 2004.